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Invited Session Summary

Title of Session Cross-Domain Collaborative Unmanned Systems Name, Salutation, Affiliation and Email of Organizers 1. Prof. Yi Yang Beijing Institute of Technology, China yang_yi@bit.edu.cn 2. Dr. Yufeng Yue

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Details of Session(including aim and scope)

Recently, cross-domain collaborative unmanned systems have attracted increasing attention due to their highly complementary perception and mobility characteristics. Cross-domain collaborative unmanned systems can be evident as physical difference between unmanned systems (UAV, UGV, USV, etc.) or as behavioral difference when unmanned systems serve diverse roles in a cooperating team. As we look to the future, cross-domain collaborative unmanned systems that can operate autonomously in complex environments remain a significant challenge. This invited session will focus on cross-domain collaborative unmanned systems, including areas of perception, localization, mapping, navigation, control, machine learning, multi-robot systems and relevant applications.

The purpose of this invited session is to create a forum for scientists, engineers and practitioners throughout the world to present the latest theoretical and technological achievements in cross-domain collaborative unmanned systems. Papers presenting newly emerging fields and applications are especially welcome. Topics to be covered in this invited session include, but not limited to, the following:

- multi-sensor fusion for cross-domain collaborative unmanned systems;
- intelligent perception for cross-domain collaborative unmanned systems;
- localization and mapping for cross-domain collaborative unmanned systems;
- autonomous navigation for cross-domain collaborative unmanned systems;
- intelligent control for cross-domain collaborative unmanned systems;
- deep learning for cross-domain collaborative unmanned systems;
- cross-domain collaborative unmanned systems applied in construction, agricultural, rescue or exploration tasks.